Gluing methods in almost-Kähler geometry

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└─Calabi's program.

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└─Calabi's program.

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Inspiration: Uniformization theorem for Riemann surfaces

Let (Σ^2, J) be a compact Riemann surface. There is a Riemannian metric g on Σ compatible with J, with constant Gauss curvature. Moreover, this metric is unique (up to isometries) if we set $Vol_g(\Sigma) = 1$. **Question:** Given a smooth compact manifold, is there a 'privileged' Riemannian metric ?

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Let (Σ^2, J) be a compact Riemann surface. There is a Riemannian metric g on Σ compatible with J, with constant Gauss curvature. Moreover, this metric is unique (up to isometries) if we set $Vol_g(\Sigma) = 1$.

- Framework: (almost)-Kähler manifolds
- 'Privileged' metrics = constant scalar curvature metrics in a fixed Kähler class.

└─Calabi's program.

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Gluing methods are a way of obtaining explicit examples. Examples: Works of Arezzo and Pacard, Szekelyhidi. Gluing in Kähler geometry: an overview.

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Gluing methods in almost-Kähler geometry Gluing in Kähler geometry: an overview.

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$$(M, J_M, \omega_M)$$
 has constant scalar curvature.

From the Kähler property, we have holomorphic coordinates around *p*:

$$\underline{z}: p \ni U \to U' \subset \mathbb{C}^m/\Gamma$$

such that

$$\omega_M = \omega_{eucl} + O(|\underline{z}|^2).$$

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We assume that (X, J_X, ω_X) has zero scalar curvature.

The 'connected sum'

Using these coordinates, we identify a small 'ring' around $p \in M$ to a large region in X via a homothety.

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Thus we obtain a *complex* smooth manifold M_{ε} .

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Then, the problem is to find $f\in\mathcal{C}^\infty(M_arepsilon)$ such that

$$s(\omega_{\varepsilon}+dd^{c}f)=\lambda.$$

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- Lejmi, Keller and Lejmi: study of Calabi's functional, Futaki's invariant
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- Lejmi, Keller and Lejmi: study of Calabi's functional, Futaki's invariant
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Question: Could we use gluing methods to obtain privileged metrics on almost-Kähler manifolds ?

We use more general ALE models (X, J_X, ω_X) :

 $\underline{u}:X\setminus K\to \mathbb{C}^m/\Gamma$

diffeomorphism outside a compact set, such that

$$\omega_X = \omega_{eucl} + O(|\underline{u}|^{2-2m})$$
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Such non-trivial resolutions only exist in complex dimension 2 (Hein, Radeasconu, Suvaina).

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 (X ≃ T*S², J_X, ω_X) ALE Kähler surface asymptotic to C²/Z₂. We explicitly obtain the ALE metric by solving Ric(dd^cφ) = 0, with φ = f(|z|²), on smoothings

$$\{z_1^2+z_2^2+z_3^2=\varepsilon\}\subset\mathbb{C}^3$$

of

$$\mathbb{C}^2/\mathbb{Z}_2 \simeq \{z_1^2 + z_2^2 + z_3^2 = 0\}.$$

The Riemannian metric g_X thus derived is Eguchi-Hanson's. The complex structure inherited from \mathbb{C}^3 verifies

$$J_X - J_{eucl} = O(|u|^{-4}).$$

Generalized connected sum.

We work in Darboux charts.

 On the orbifold: an equivariant version of Darboux's theorem near p gives

$$\underline{x}: p \ni U \to U' \subset \mathbb{C}^2/\mathbb{Z}_2$$

such that ω_M coincides with ω_{eucl} . Moreover

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 On the ALE surface: Performing an explicit change of variables, we get

$$\underline{u}: X \setminus K \to (\mathbb{C}^2 \setminus B(0, R))/\mathbb{Z}_2$$

such that ω_X coincides with ω_0 . Moreover, we recover

$$J_X - J_{eucl} = O(|\underline{u}|^{-4}).$$

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Using these charts to perform the connected sum construction gives us a family of *symplectic* manifolds $(M_{\varepsilon}, \omega_{\varepsilon})$.

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- 2 The zero section of $X \simeq T^*S^2$ provides a Lagrangian sphere S in $(\tilde{M}, \tilde{\omega})$.

We want to

- = endow M_{ε} with an almost complex structure compatible with ω_{ε} .
- perturb this structure into a 'canonical' one.

Almost complex structures on $(M_{\varepsilon}, \omega_{\varepsilon})$.

We use the following description of \mathcal{AC}_{ω} on a symplectic manifold (V, ω) .

Theorem

Let (V, ω) be a symplectic manifold. We set

$$\operatorname{End}(TV,\omega) = \{a \in \operatorname{End}(TV), \, \omega(aX,Y) + \omega(X,aY) = 0\},\$$

the Lie algebra of automorphisms of TV that preserve ω . Then, if $J_1, J_2 \in \mathcal{AC}_{\omega}$, there exists $a \in \mathcal{C}^{\infty}(\operatorname{End}(TV, \omega))$ such that

$$J_2 = \exp(a)J_1\exp(-a).$$

Using this description and suitable cut-off functions, we get an a.c.s. $J_{r_{\varepsilon}}$ on M, compatible with ω_M , such that

$$J_{r_{\varepsilon}} = \begin{cases} J_0 \text{ on } \{|\underline{x}| \leq 2r_{\varepsilon}\} \\ J_M \text{ on } \{|\underline{x}| \geq 4r_{\varepsilon}\} \end{cases}$$

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Remarks:

1 J_{ε} is not integrable, but $N_{J_{\varepsilon}}$ is supported in the gluing region $\{r_{\varepsilon} \leq |\underline{x}| \leq 4r_{\varepsilon}\}$, and controlled in suitable norms by a positive power of ε .

2 The Lagrangian sphere S_{ε} is minimal for g_{ε} .

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$$\omega_f := \omega_\varepsilon + dJ_\varepsilon df$$

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$$J_f := \exp(-a_f) J_{\varepsilon} \exp(a_f).$$

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The equation (1) is a fourth order PDE on f.

Gluing methods in almost-Kähler geometry └─ In the almost-Kähler framework.

Strategy.

We imitate the proof of the Inverse Function Theorem. We linearise:

$$L_{\varepsilon}(f) := \frac{d}{dt}|_{t=0} s^{\nabla}(J_{tf}),$$

thus

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The linearised operator is given by

$$\begin{split} \mathcal{L}_{\varepsilon}f &= -\Delta_{g_{\varepsilon}}^{2}f + 2\delta_{g_{\varepsilon}}\mathsf{Ric}_{g_{\varepsilon}}(\mathsf{grad}_{g_{\varepsilon}}f, \cdot) + \mathcal{E}_{\varepsilon}f \\ &= \mathbb{L}_{M_{\varepsilon}}f + \mathcal{E}_{\varepsilon}f, \end{split}$$

where \mathbb{L} is the *Lichnerowicz operator* on M_{ε} , and the error term E_{ε} is small in suitable norms, with coefficients comparable to the Nijenhuis tensor $N_{J_{\varepsilon}}$.

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- 3 Control the non-linear term Q_{ε} .

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Right inverse of the linearisation.

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These operators are defined on *noncompact* manifolds: in terms of regularity property, they do not behave well in usual Hölder spaces $\mathcal{C}^{k,\alpha}(M^*)$, $\mathcal{C}^{k,\alpha}(X)$ (ex: Schauder estimates are lost).

Gluing methods in almost-Kähler geometry └─ In the almost-Kähler framework.

Weighted Hölder spaces

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• On M^* : $\phi \in C^{k,\alpha}_{\delta}(M^*)$ if $\phi \in C^{k,\alpha}_{\text{loc}}(M^*)$ and ϕ behaves 'at worst' like $|\underline{x}|^{\delta}$ near the puncture p.

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- On X: ψ ∈ C^{k,α}_δ(X) if ψ ∈ C^{k,α}_{loc}(X) and ψ behaves 'at worst' like |<u>u</u>|^δ at infinity.
- On M_{ε} : We decompose $f \in C^{k,\alpha}_{loc}(M_{\varepsilon})$ into $f = \gamma_1 f + \gamma_2 f$, où $\gamma_1 f \in C^{k,\alpha}_{loc}(M^*)$ and $\gamma_2 f \in C^{k,\alpha}_{loc}(X)$. Then we set

$$\|f\|_{\mathcal{C}^{k,\alpha}_{\delta}(M_{\varepsilon})} = \|\gamma_{1}f\|_{\mathcal{C}^{k,\alpha}_{\delta}(M^{*})} + \varepsilon^{-\delta}\|\gamma_{2}f\|_{\mathcal{C}^{k,\alpha}_{\delta}(X)}$$

In these spaces, the model operators have the expected behavior:

Proposition

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• Let $\xi \in C^{\infty}(M)$ supported in $B(p, 2r_0)$ and equal to 1 in $B(p, r_0)$. Then

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• $\mathbb{L}_X : \mathcal{C}^{4,\alpha}_{\delta}(X) \to \mathcal{C}^{0,\alpha}_{\delta-4}(X)$ admits a right inverse G_2 .

Gluing methods in almost-Kähler geometry └─ In the almost-Kähler framework.

Right inverse for \tilde{L}_{ε}

From there we get:

Theorem

For $0 < \delta < 1$, for ε small enough, the operator

$$ilde{\mathcal{L}}_arepsilon: \mathcal{C}^{4,lpha}_\delta(M_arepsilon) imes \mathbb{R} o \mathcal{C}^{0,lpha}_{\delta-4}(M_arepsilon)$$

admits a right inverse G_{ε} , such that $\|G_{\varepsilon}\| \leq \varepsilon^{-\delta\beta}$, with $0 < \beta < 1$.

Outline of proof: We glue together G_1 and G_2 into an 'approximate right inverse': for $f \in C^{0,\alpha}_{\delta-4}(M_{\varepsilon})$, se set

$$ilde{\mathcal{G}}_arepsilon(f) = \zeta_1 \mathcal{G}_1(\gamma_1 f) + \zeta_2 \mathcal{G}_2(\gamma_2 f).$$

Outline of proof: We glue together G_1 and G_2 into an 'approximate right inverse': for $f \in C^{0,\alpha}_{\delta-4}(M_{\varepsilon})$, se set

$$\widetilde{G}_{\varepsilon}(f) = \zeta_1 G_1(\gamma_1 f) + \zeta_2 G_2(\gamma_2 f).$$

Then we show that:

$$\|\tilde{L}_{\varepsilon}\circ\tilde{G}_{\varepsilon}-I\|\xrightarrow{\varepsilon\to 0} 0.$$

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Then we show that:

$$\|\widetilde{L}_{\varepsilon}\circ\widetilde{G}_{\varepsilon}-I\|\xrightarrow{\varepsilon\to 0}0.$$

Thus, $G_{\varepsilon} := \tilde{G}_{\varepsilon} \circ (\tilde{L}_{\varepsilon} \circ \tilde{G}_{\varepsilon})^{-1}$ is a genuine right inverse for \tilde{L}_{ε} .

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Definition. Euler-Lagrange equation.

Definition

Let (V, ω, J, g) be an almost-Kähler manifold. A Lagrangian submanifold L of V is *Hamiltonian-stationary* if

$$\frac{d}{ds}_{|s=0} \operatorname{Vol}_g(\exp(sX_F)(L)) = 0$$

for any $F \in \mathcal{C}^{\infty}(L)$.

Definition. Euler-Lagrange equation.

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Let H be the mean curvature vector field of L. We define the Maslov-form $\alpha := H \,\lrcorner\, \omega$.

Then the Euler-Lagrange equation associated to the variational problem is

$$\delta \alpha = 0.$$

Construction of Hamiltonian-stationary spheres.

In our setting, we essentially obtained a sympectic manifold $(\tilde{M}, \tilde{\omega})$ endowed with

- a Lagrangian sphere S;
- a family of metrics with constant Hermitian scalar curvature $(\tilde{J_{\varepsilon}}, \tilde{g}_{\varepsilon})$.

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Question: For ε small enough, can we find a function F_{ε} such that $\exp(X_{F_{\varepsilon}})(S)$ be Hamiltonian-stationary for $(\tilde{g}_{\varepsilon}, \tilde{J}_{\varepsilon})$?

Answer: Yes ! The idea is to study the operator

$$egin{aligned} B : \mathcal{C}^{2,lpha}(\mathcal{AC}_{\widetilde{\omega}}) imes \mathcal{C}^{4,lpha}(S) o \mathcal{C}^{0,lpha}(S) \ (J,F) \mapsto \delta_{J,F} lpha_{J,F} \end{aligned}$$

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$$B: \mathcal{C}^{2,\alpha}(\mathcal{AC}_{\tilde{\omega}}) \times \mathcal{C}^{4,\alpha}(S) \to \mathcal{C}^{0,\alpha}(S)$$
$$(J,F) \mapsto \delta_{J,F}\alpha_{J,F}$$

We have $B(\widetilde{J}_0,0)=0$.

On the other hand, the linearisation of B at $(\tilde{J}_0, 0)$ with respect to the second variable is $\Delta^2_{\tilde{g}_0}$ (Oh's formula).

This allows us to use the Implicit Function Theorem.

Conclusion and perspectives

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Through the gluing construction, we have obtained a symplectic manifold $(\tilde{M},\tilde{\omega})$ endowed with

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- a family of Lagrangian spheres S_{ε} that is Hamiltonian-stationary for \tilde{g}_{ε} .

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- a family of Lagrangian spheres S_ε that is Hamiltonian-stationary for g̃_ε.

Perpectives

- Other types of singularities;
- Higher dimensions, for instance smoothings of double points;
- Can the blow-up construction be made in a way to preserve the constant curvature condition ?

Gluing methods in almost-Kähler geometry

Hamiltonian stationary spheres.

Thank you for your attention !